

ECEN689: Special Topics in High-Speed Links Circuits and Systems Spring 2010

Lecture 22: ISI and Random Noise



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Announcements

- HW6 due Wednesday April 7 (in class)
- Exam 2 will be either April 28 or 30
- Reading
 - Dally 6.1-6.3

Agenda

- Common noise sources
 - ISI
 - Random noise

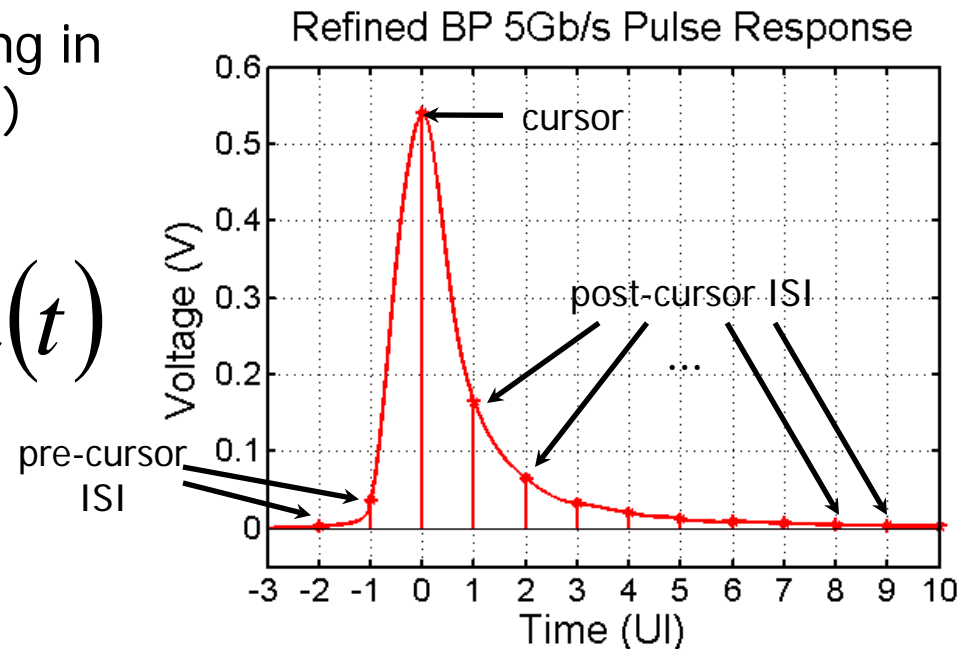
Common Noise Sources

- Power supply noise
- Receiver offset
- Crosstalk
- Inter-symbol interference
- Random noise

Inter-Symbol Interference (ISI)

- Previous bits residual state can distort the current bit, resulting in inter-symbol interference (ISI)

$$y^{(d_k)}(t) = c^{(d_k)}(t) * h(t)$$



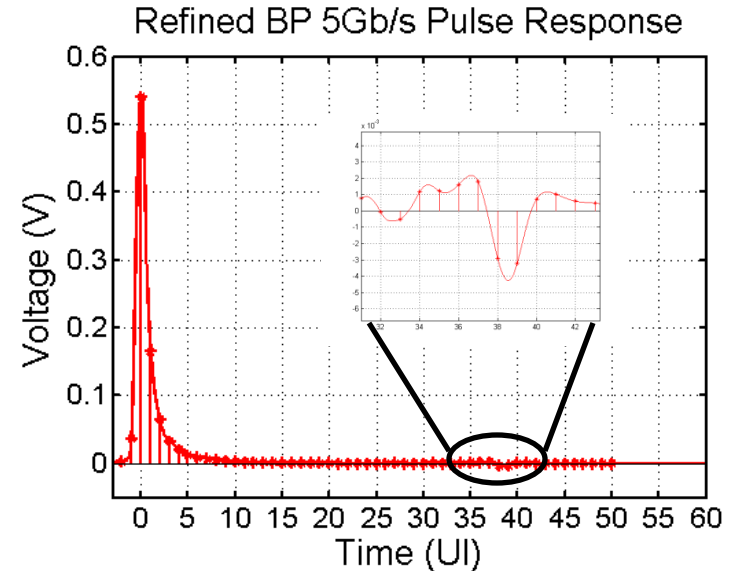
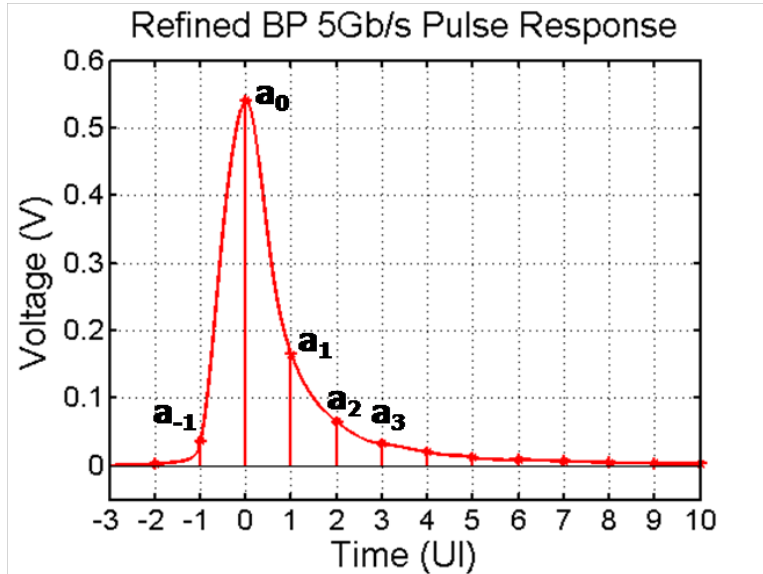
$y^{(1)}(t)$ sampled relative to pulse peak:

[... 0.003 0.036 0.540 0.165 0.065 0.033 0.020 0.012 0.009 ...]

$k = [\dots -2 \quad 1 \quad 0 \quad 1 \quad 2 \quad 3 \quad 4 \quad 5 \quad 6 \quad \dots]$

By Linearity: $y^{(0)}(t) = -1 * y^{(1)}(t)$

Peak Distortion Analysis Example

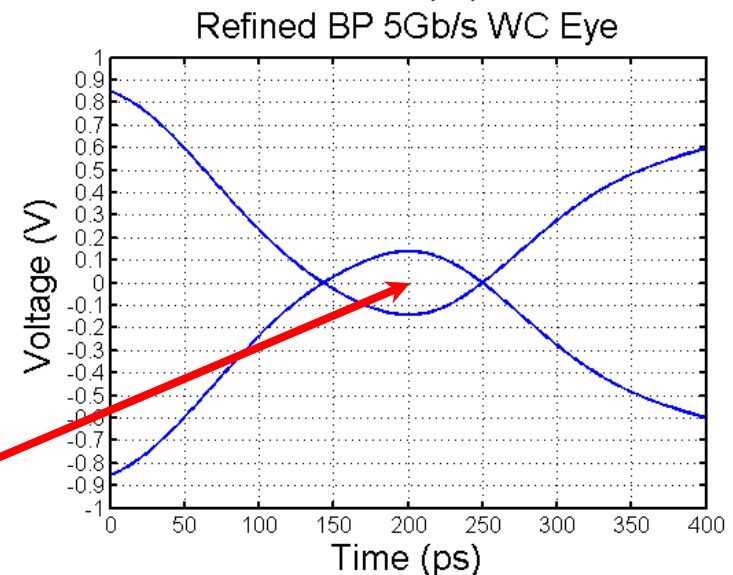


$$y_0^{(1)}(t) = 0.540$$

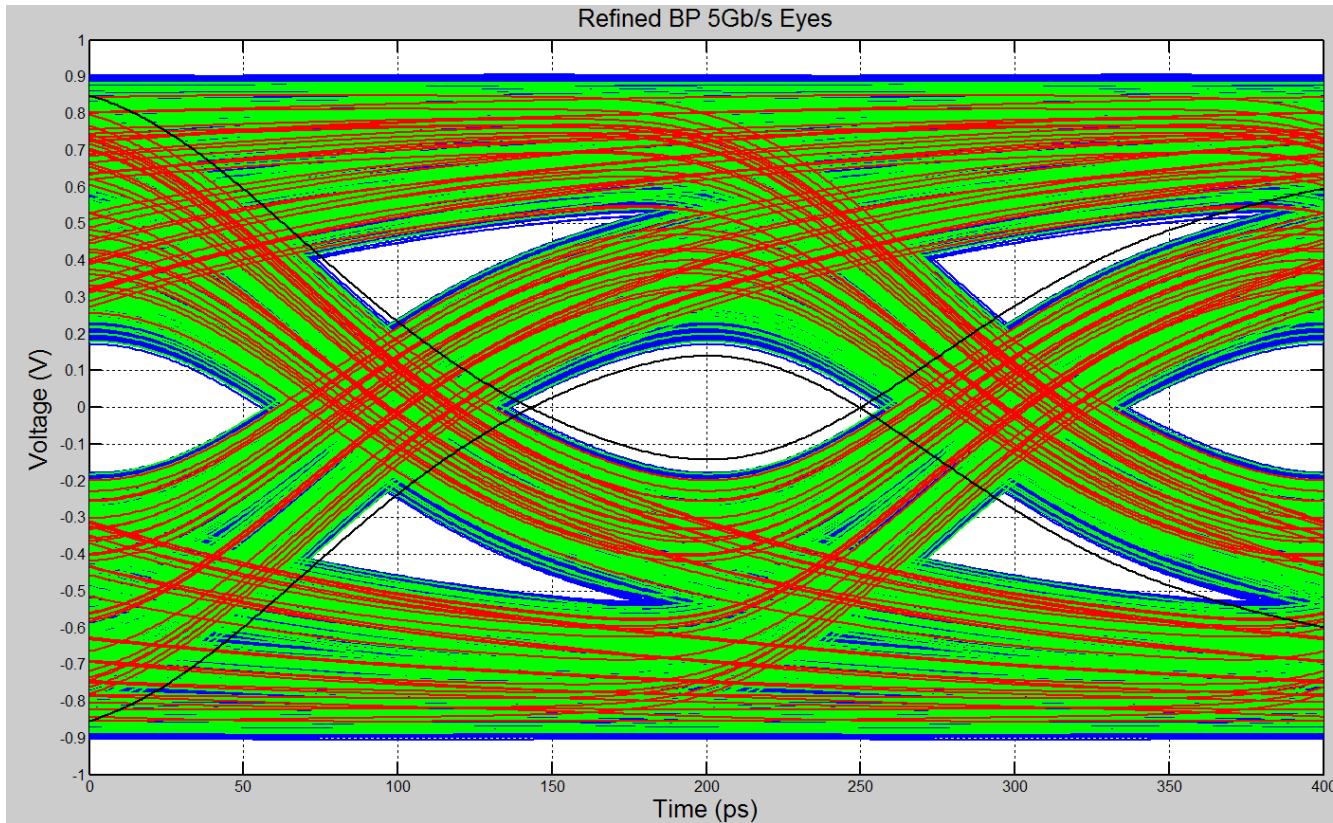
$$\sum_{\substack{k=-\infty \\ k \neq 0}}^{\infty} y^{(1)}(t-kT) \Big|_{y(t-kT) < 0} = -0.007$$

$$\sum_{\substack{k=-\infty \\ k \neq 0}}^{\infty} y^{(1)}(t-kT) \Big|_{y(t-kT) > 0} = 0.389$$

$$s(t) = 2(0.540 - 0.007 - 0.389) = 0.288$$



Worst-Case Eye vs Random Data Eye

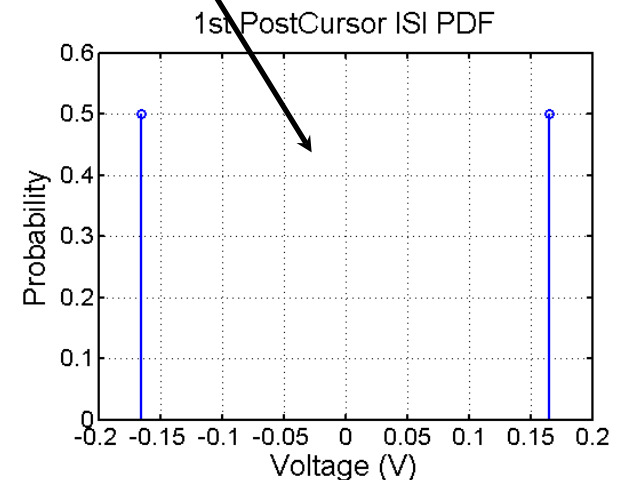
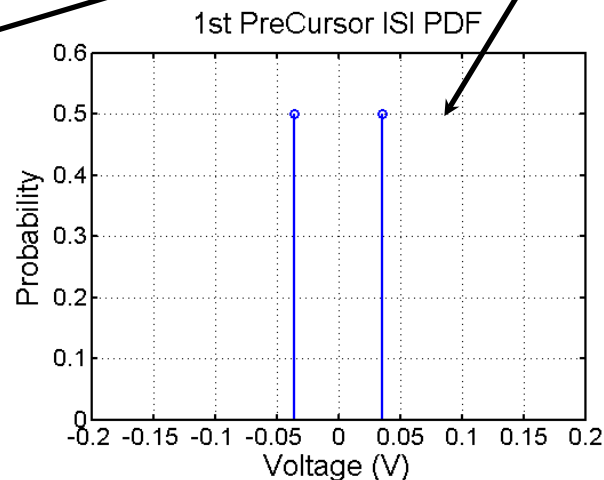
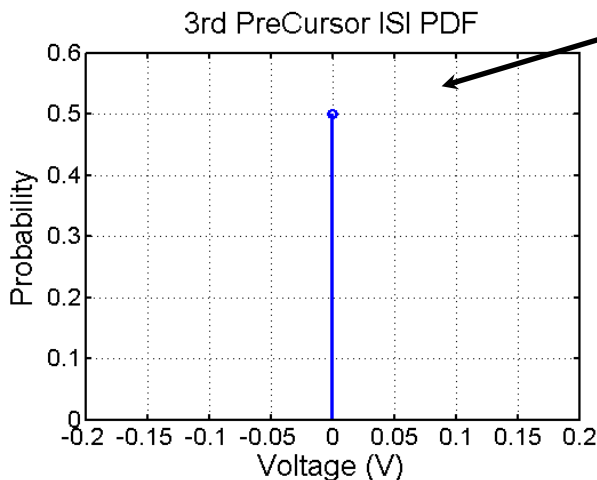
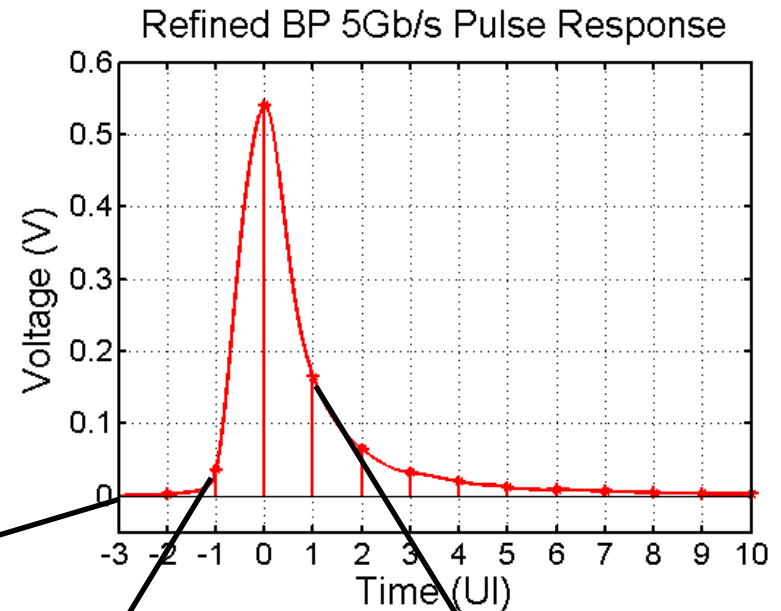


Worst-Case Eye
100 Random Bits
1000 Random Bits
1e4 Random Bits

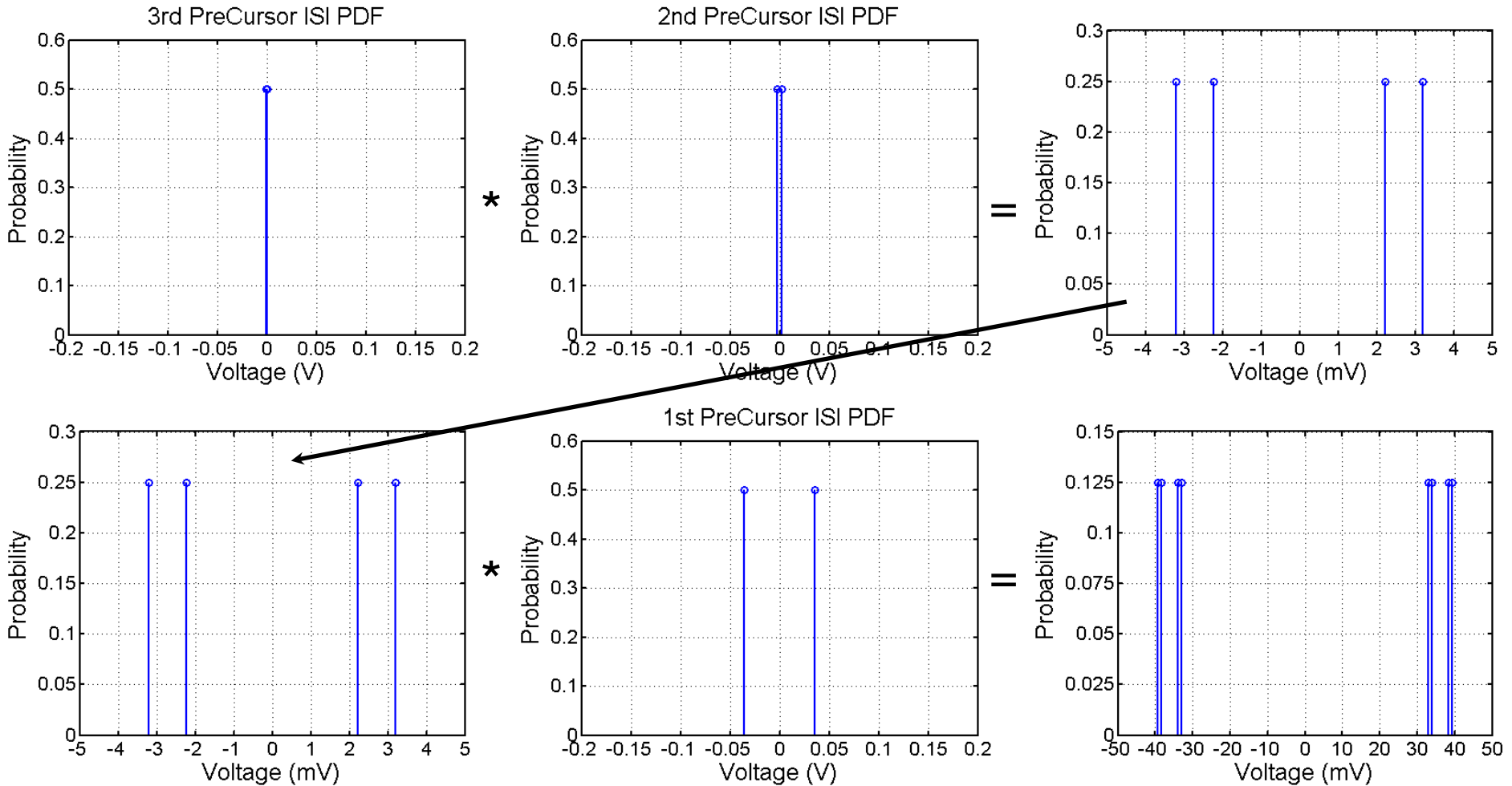
- Worst-case data pattern can occur at very low probability!
- Considering worst-case is too pessimistic

Constructing ISI Probability Density Function (PDF)

- Using ISI probability density function will yield a more accurate BER performance estimate
- In order to construct the total ISI PDF, need to convolve all of the individual ISI term PDFs together
 - 50% probability of "1" symbol ISI and "-1" symbol ISI

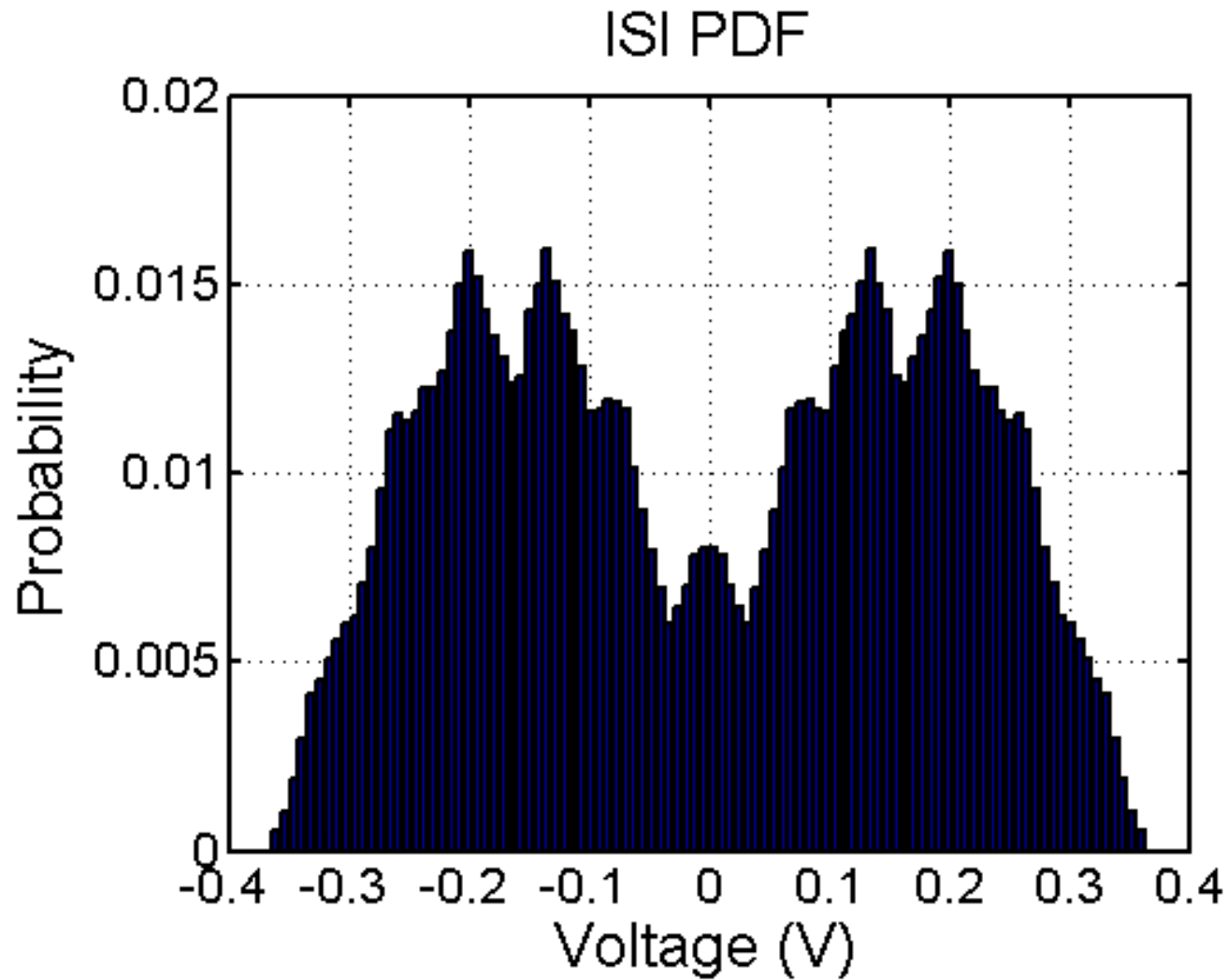


Convolving Individual ISI PDFs Together

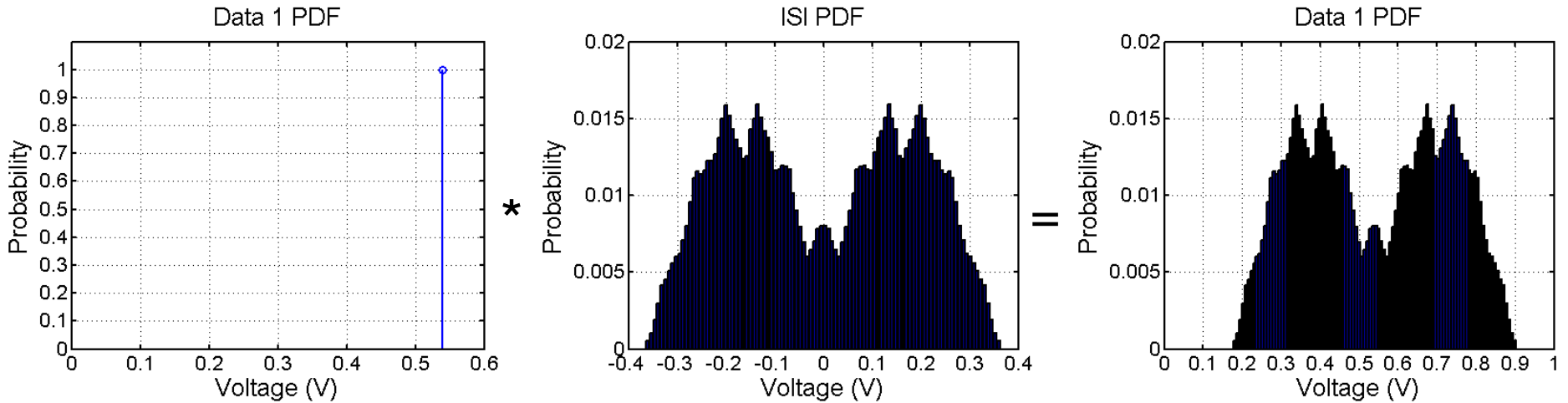


- Keep going until all individual PDFs convolved together

Complete ISI PDF



Cursor PDF – Data 1

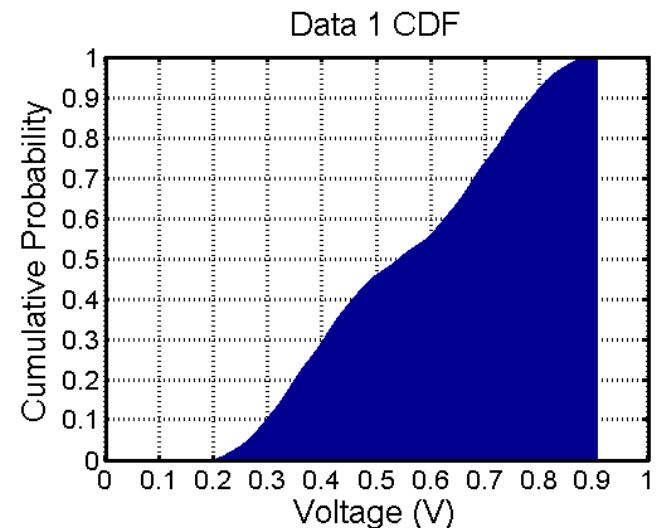
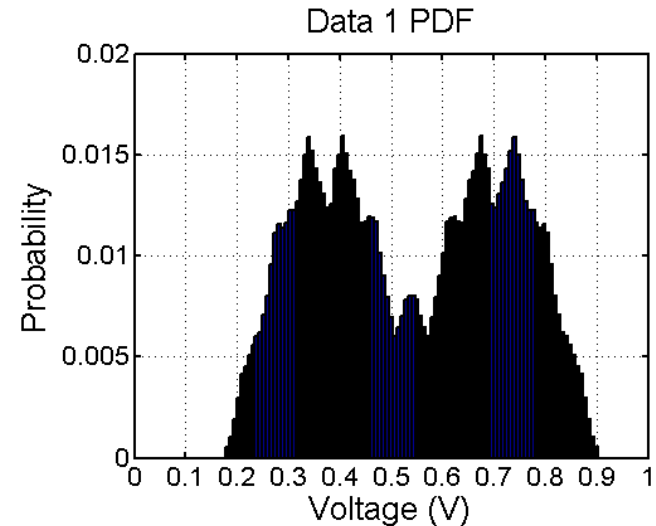


- Data 1 PDF is centered about the cursor value and varies from a maximum positive value to the worst-case value predicted by PDA
 - This worst-case value occurs at a low probability!

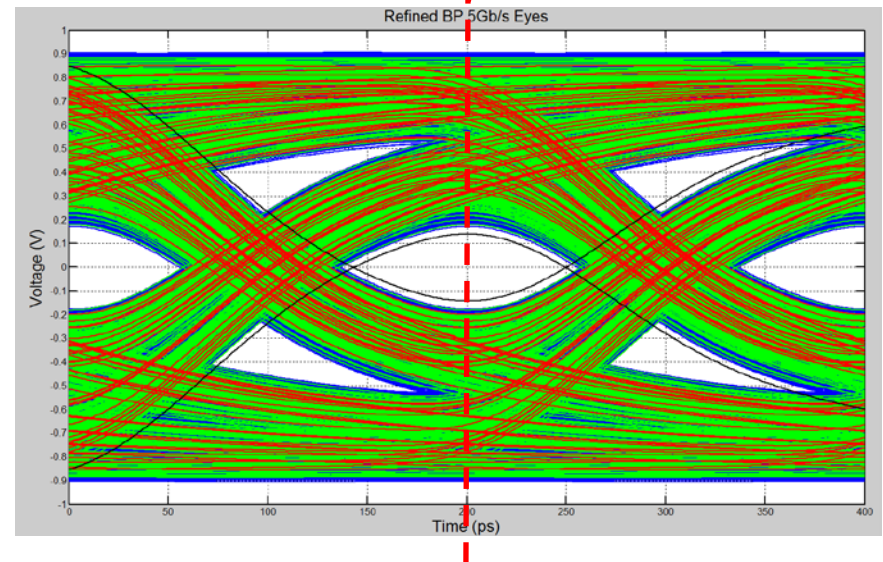
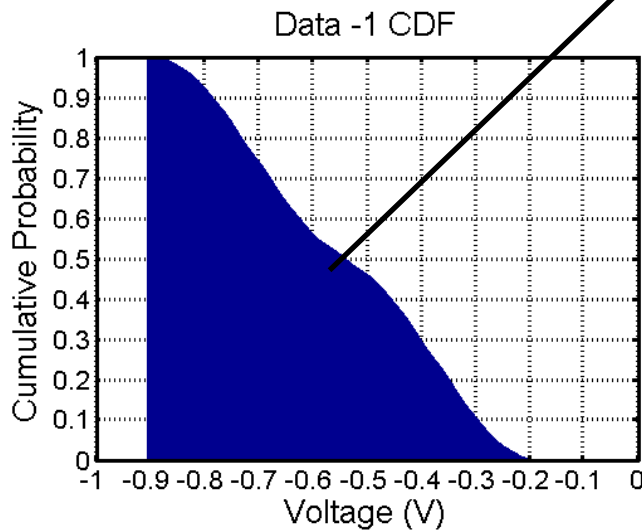
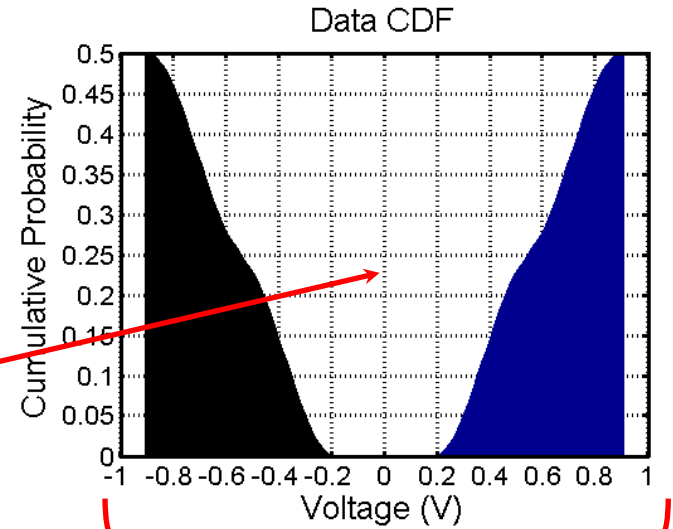
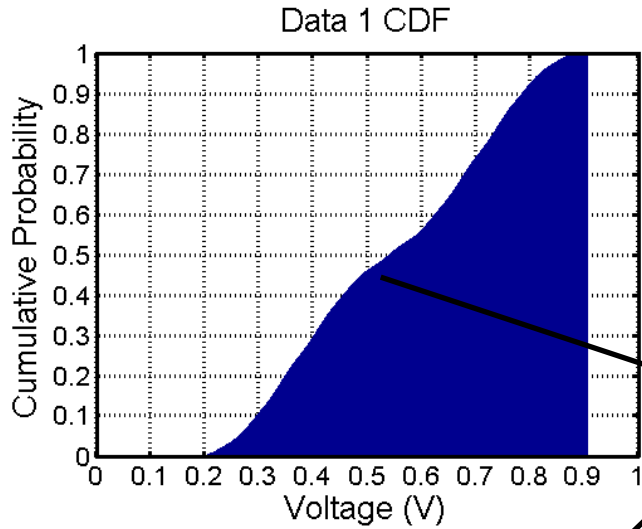
Cursor Cumulative Distribution Function (CDF)

- Data 1 error probability for a given offset is equal to the Data 1 CDF

$$BER(X) = \int_{-\infty}^X (PDF) dx$$

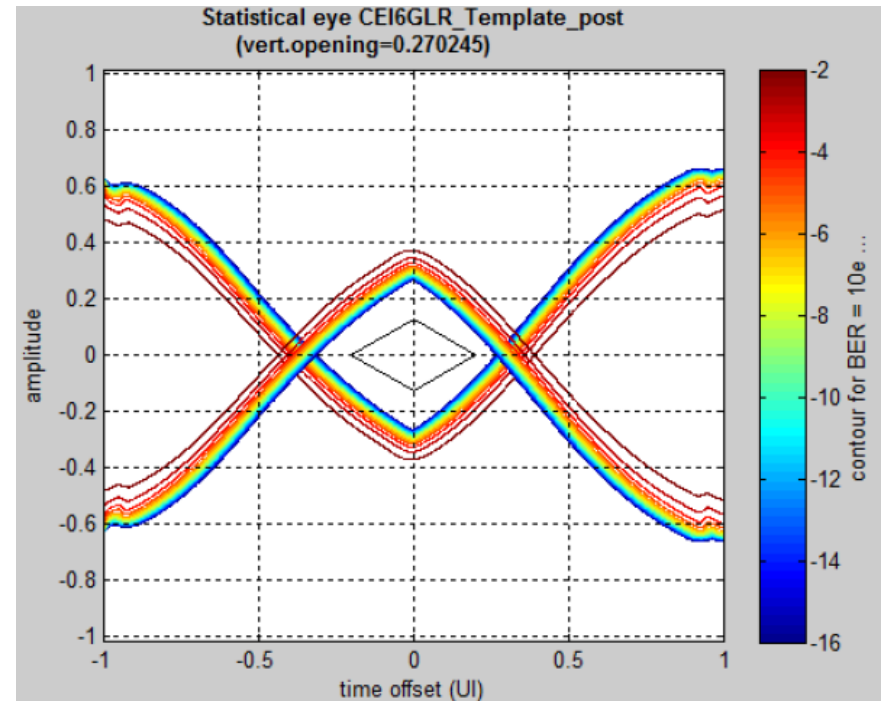


Combining Cursor CDFs



Bit-Error-Rate (BER) Distribution Eye

- Statistical BER analysis tools use this technique to account for ISI distribution and also other noise sources
 - Example from Stateye
 - Note: Different channel & data rate from previous slides



Common Noise Sources

- Power supply noise
- Receiver offset
- Crosstalk
- Inter-symbol interference
- Random noise

Random Noise

- Random noise is unbounded and modeled statistically
 - Example: Circuit thermal and shot noise
- Modeled as a continuous random variable described by
 - Probability density function (PDF)
 - Mean, μ
 - Standard deviation, σ

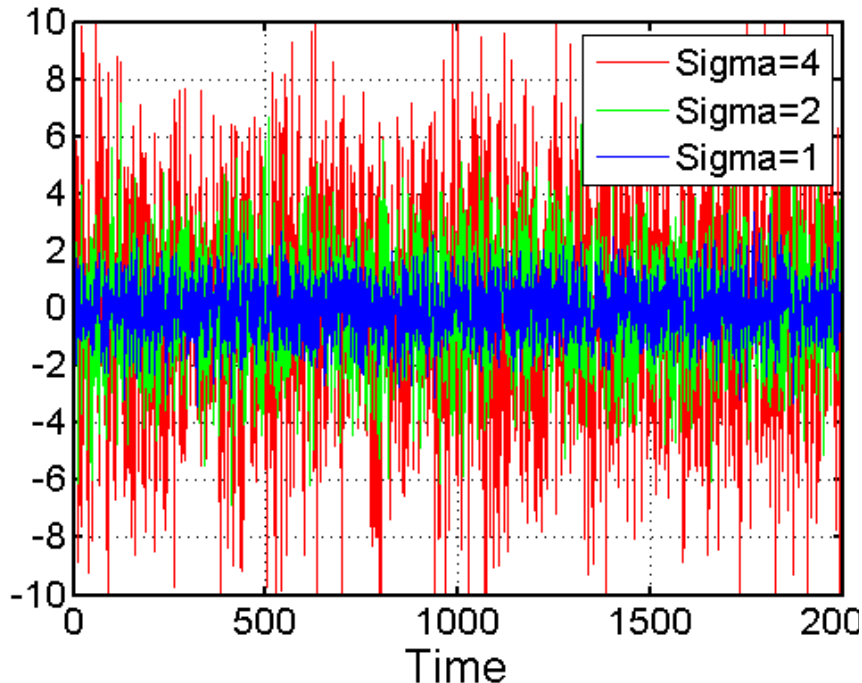
$$PDF = P_n(x), \quad \mu_n = \int_{-\infty}^{\infty} xP_n(x)dx, \quad \sigma_n^2 = \int_{-\infty}^{\infty} (x - \mu_n)^2 P_n(x)dx$$

Gaussian Distribution

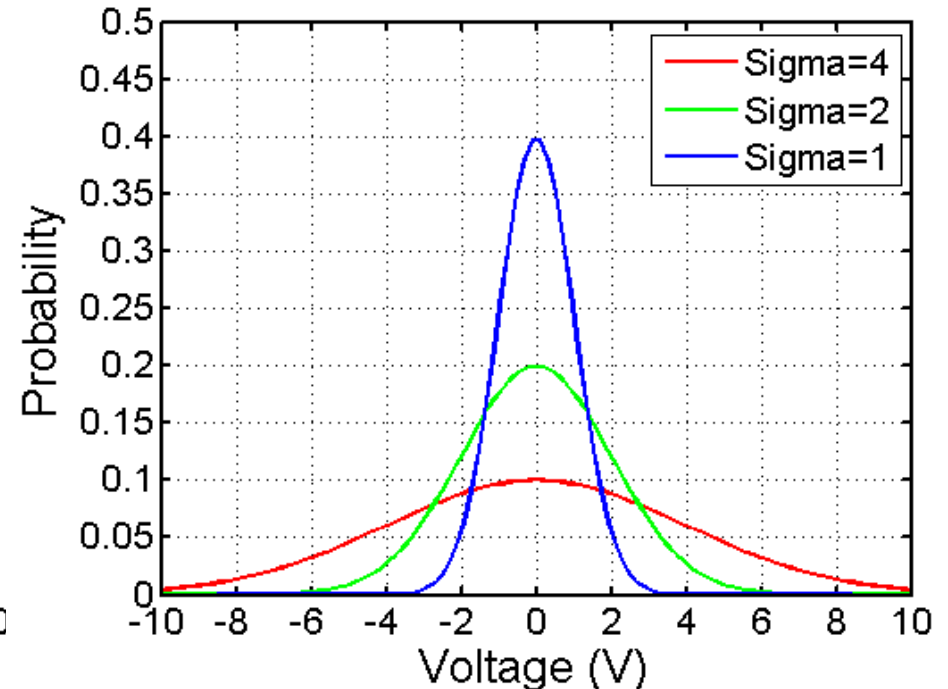
- Gaussian distribution is normally assumed for random noise
 - Larger sigma value results in increased distribution spread

$$P_n(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu_n)^2}{2\sigma^2}}$$

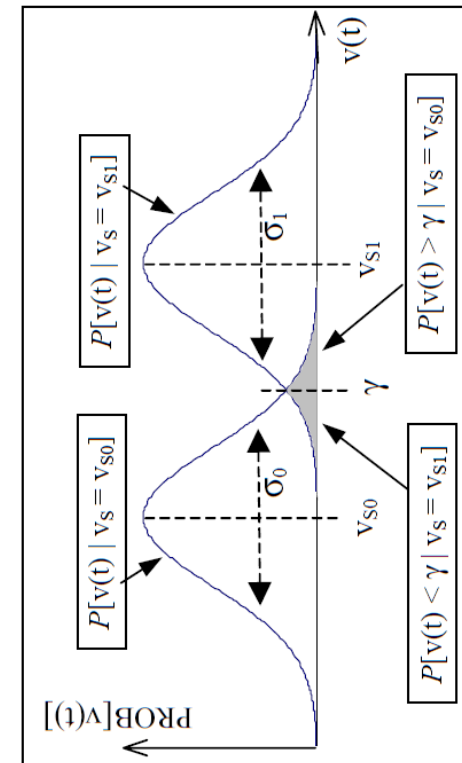
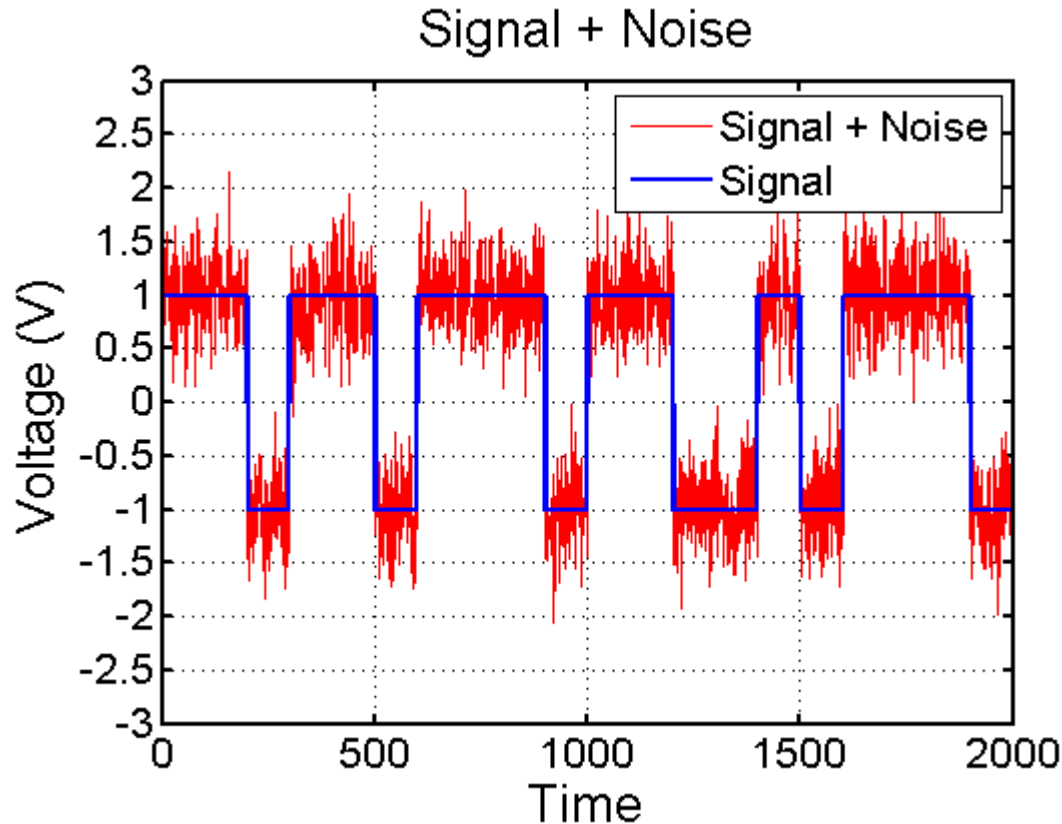
Gaussian Noise



Gaussian PDFs



Signal with Added Gaussian Noise

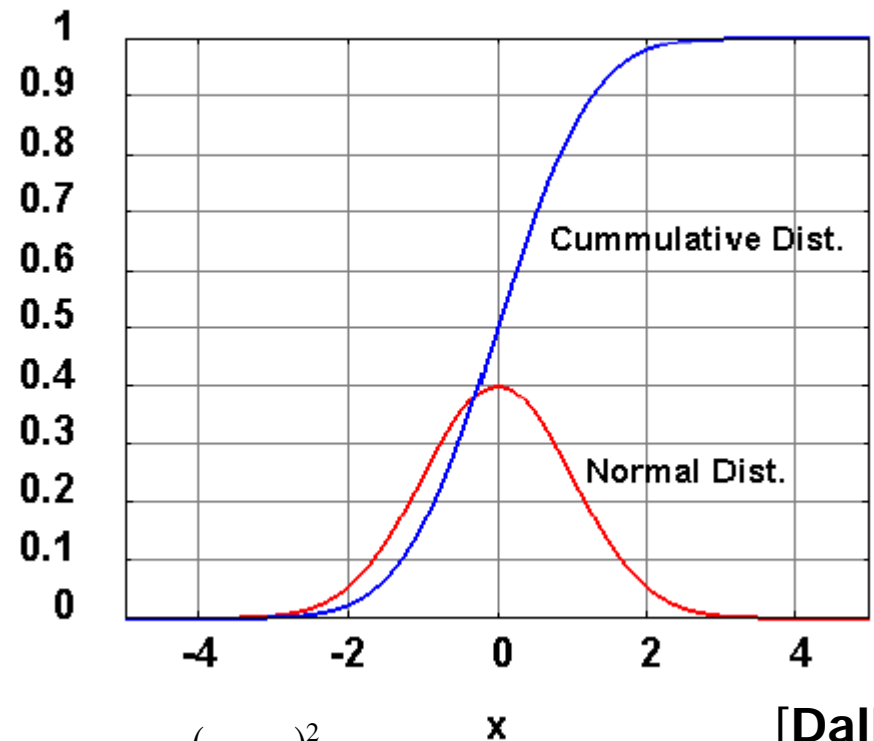


- Finite probability of noise pushing signal past threshold to yield an error

Cumulative Distribution Function (CDF)

- The CDF tells what is the probability that the noise signal **exceeds** a certain value

Standard Normal & Cumulative Distributions



$$\Phi_n(x) = \int_{u=-\infty}^x P_n(u) du = \int_{u=-\infty}^x \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(u-\mu_n)^2}{2\sigma^2}} du$$

[Dally]

Error and Complimentary Error Functions

- Error Function:

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_{u=0}^x \exp(-u^2) du$$

- Relationship between normal CDF and Error Function:

$$\Phi(x) = \frac{1}{2} \left[1 + \operatorname{erf} \left(\frac{x}{\sqrt{2}} \right) \right]$$

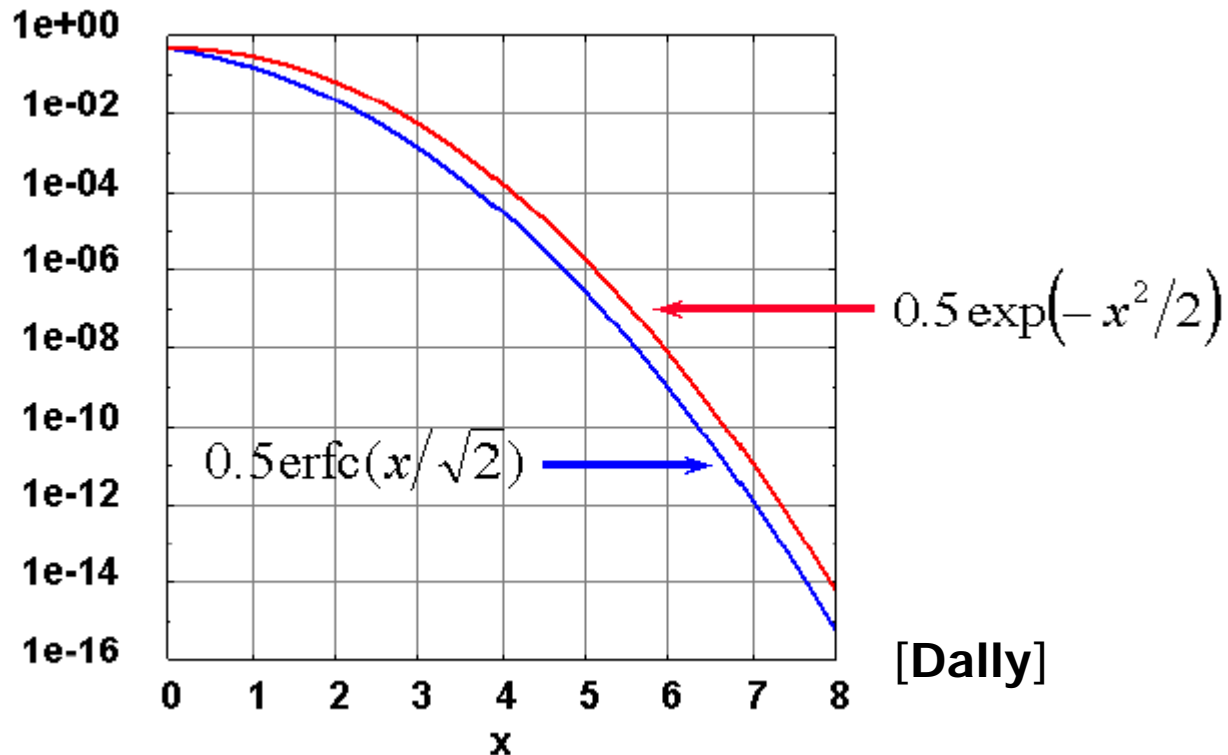
- The complementary error function gives the probability that the noise will exceed a given value

$$\begin{aligned} Q(x) &= 1 - \Phi(x) = \frac{1}{2} \left[1 - \operatorname{erf} \left(\frac{x}{\sqrt{2}} \right) \right] \\ &= \frac{1}{2} \operatorname{erfc} \left(\frac{x}{\sqrt{2}} \right) \end{aligned}$$

$$Q_{\mu\sigma}(x) = \frac{1}{2} \operatorname{erfc} \left(\frac{x - \mu}{\sigma\sqrt{2}} \right)$$

Bit Error Rate (BER)

- Using erfc to predict BER:



- Need a symbol of about 7σ for $\text{BER}=10^{-12}$
 - Peak-to-peak value will be $2x$ this

Next Time

- Noise Sources
- Timing Noise
- BER Analysis Techniques